

Large-Scale Knowledge Processing

# Using Binary Decision Diagrams (1)

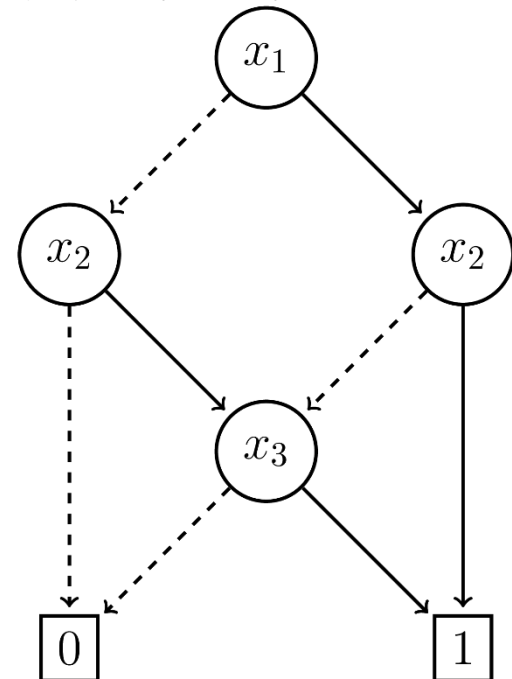


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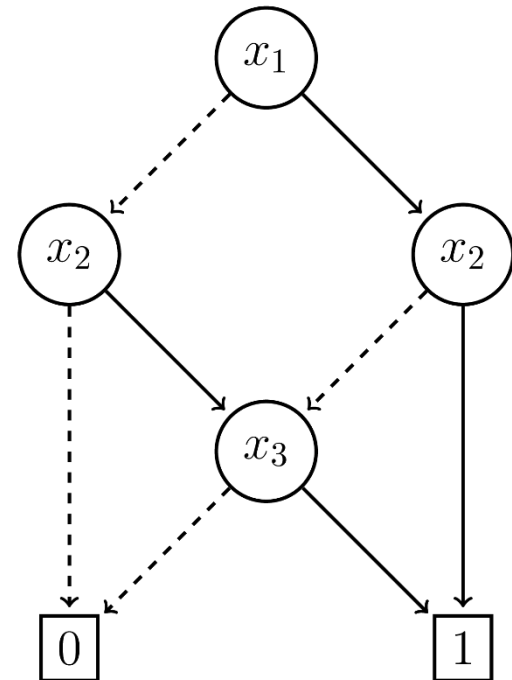
# Prev. class: Binary Decision Diagram (BDD)

- Representation of Boolean functions by a **directed acyclic graph**
- **Variable order**
  - Variables appear according to a total order
- Two rules for simplifying BDDs
  - Remove **redundant nodes**
  - Share **equivalent nodes**
  - **Reduce** BDDs until we have no redundant and equivalent nodes



# Prev. class: Binary Decision Diagram (BDD)

- Representation of Boolean functions by a **directed acyclic graph**
- The **representation is unique** if variable order is defined
- Many practical Boolean functions are **compactly** represented  
(We can efficiently compress logical structures)
- **Efficient operations** for BDDs  
[Bryant 1986]
- Applications in various fields

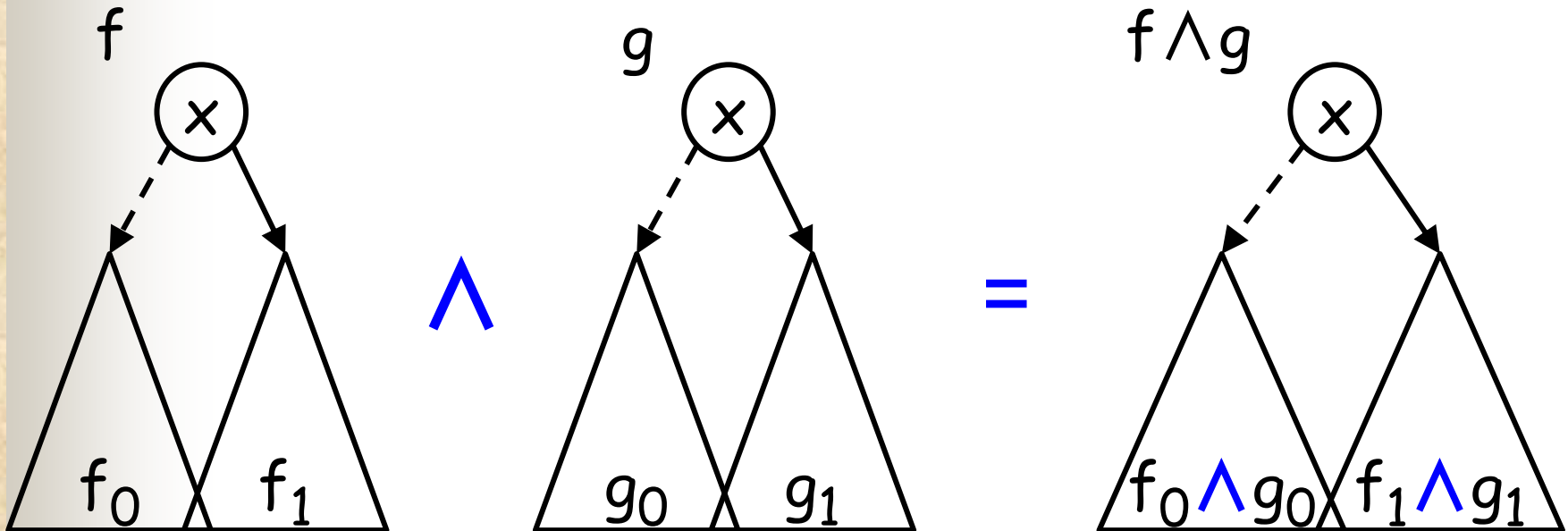


# Logical operations (Boolean operations)

- Logical AND of  $f = \overline{x} f_0 \vee x f_1$   
and  $g = \overline{x} g_0 \vee x g_1$

- $f \wedge g = \overline{x} (\underline{f_0 \wedge g_0}) \vee x (\underline{f_1 \wedge g_1})$

We can obtain these ANDs recursively



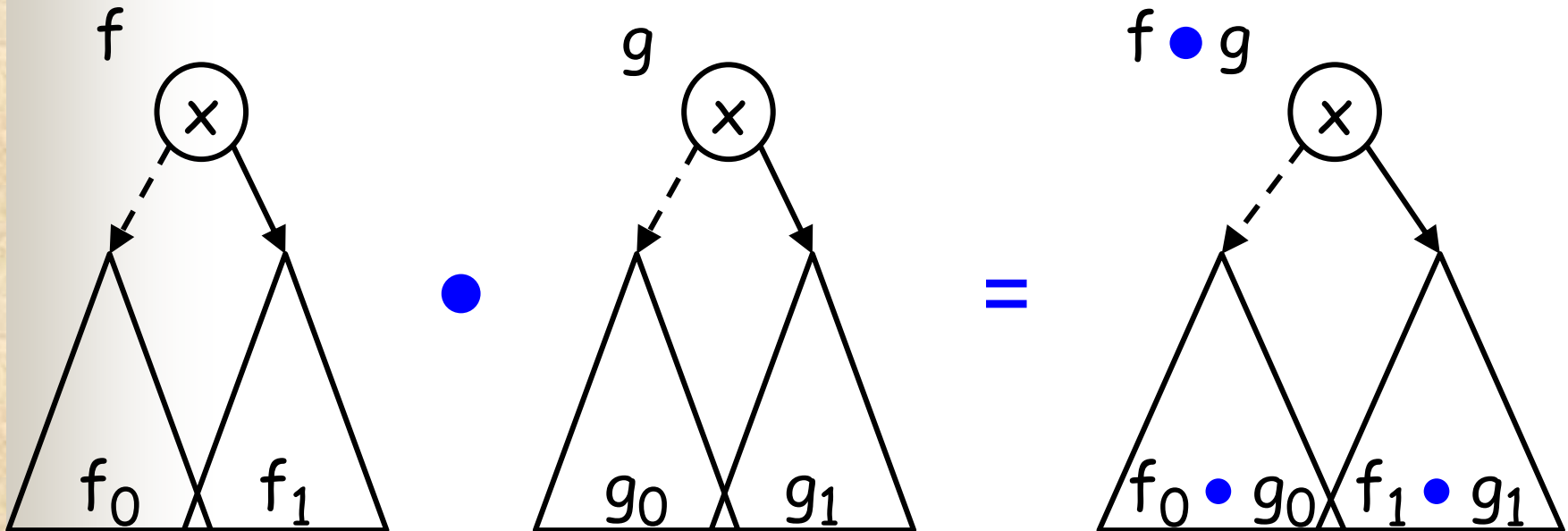
# Logical operations (Boolean operations)

AND, OR, XOR, ...

- Binary operation of  $f = \overline{x} f_0 \vee x f_1$   
and  $g = \overline{x} g_0 \vee x g_1$

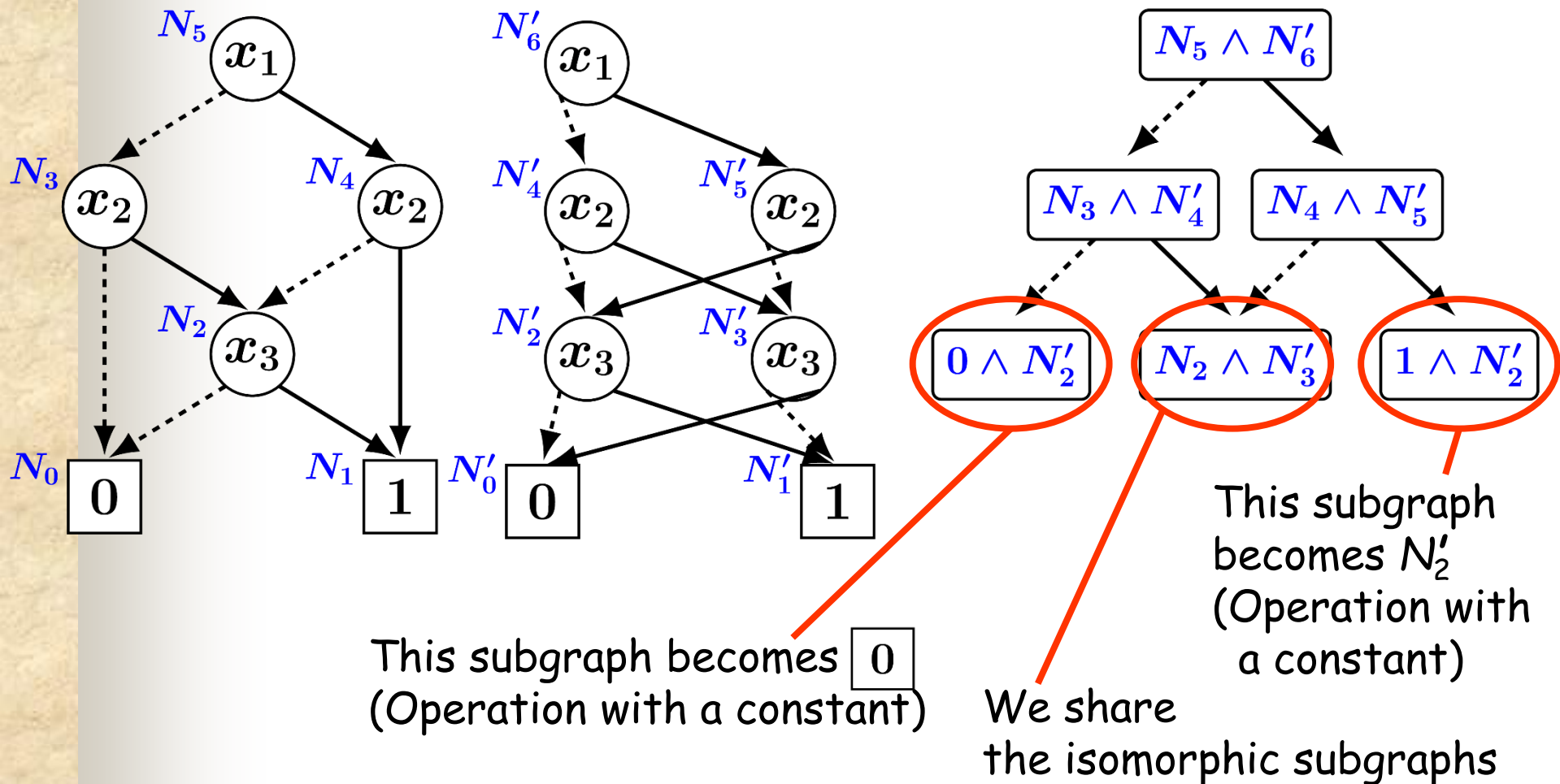
- $f \bullet g = \overline{x} (\underline{f_0 \bullet g_0}) \vee x (\underline{f_1 \bullet g_1})$

We can obtain these recursively



# practice: Apply logical operations

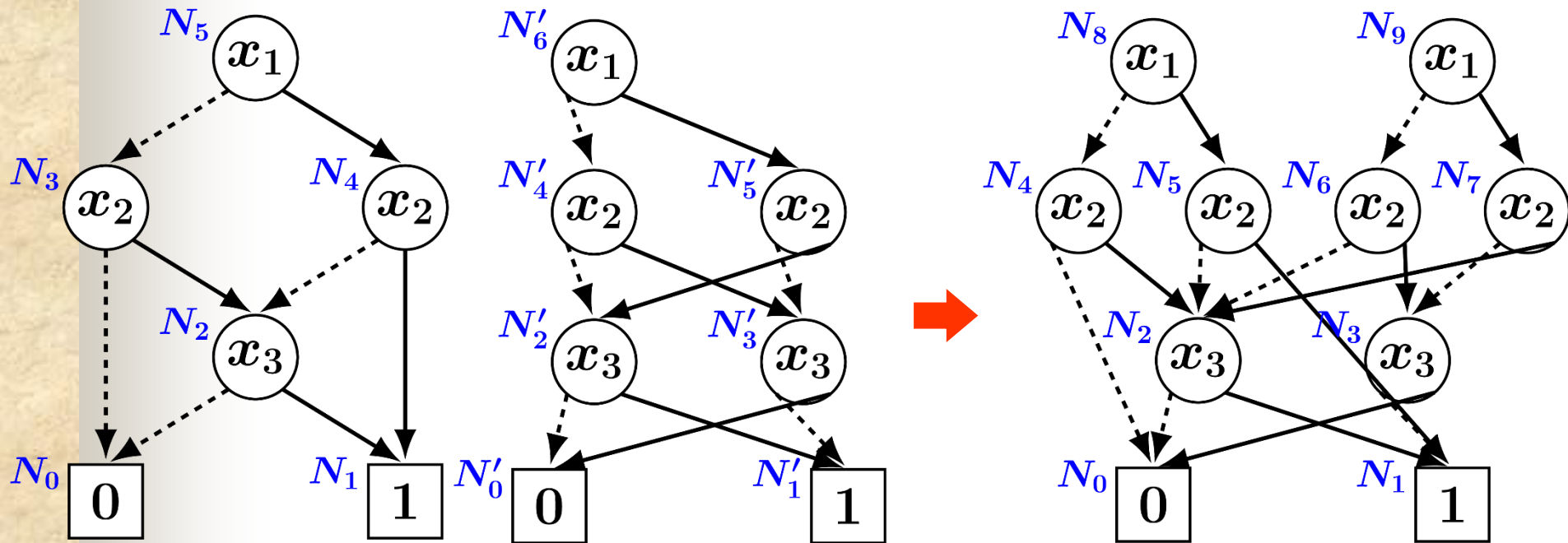
- Logical AND of the following two BDDs



# Short break

- Take a deep breath, and relax yourself

# Shared BDDs

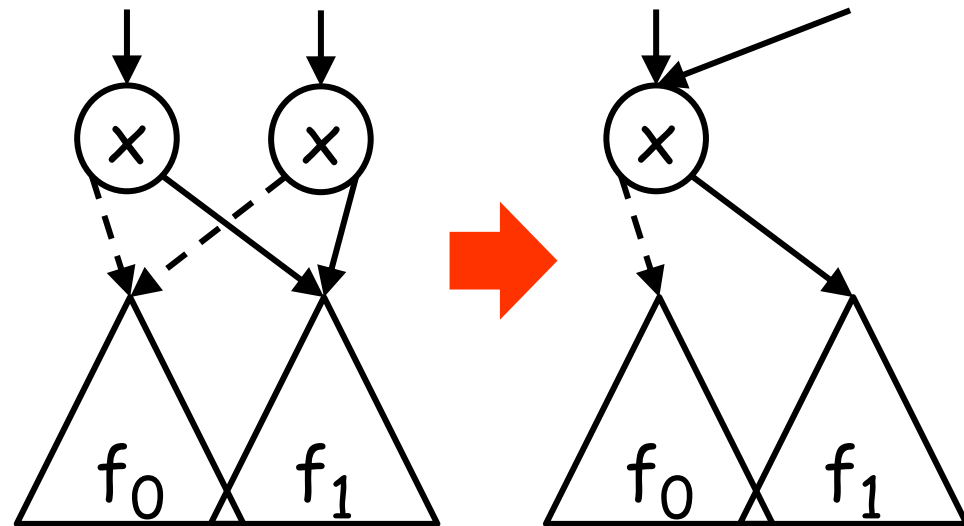


- By using the same variable order for representing BDDs, we can **share equivalent nodes** of two (or more) **BDDs**
- **Uniqueness** of Boolean functions in a BDD management system (No two BDDs represent the same Boolean function)

# Management system: Ensure uniqueness

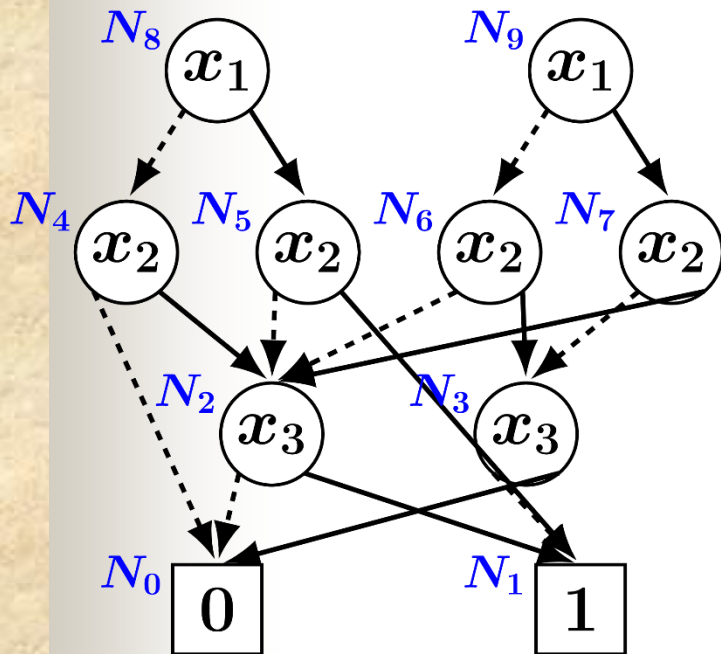
- **Equivalent nodes should be shared**  
(No equivalent nodes in a BDD management system)

Share **equivalent nodes**



- In a BDD management system, **node  $v$**  is **represented** as a **triple** of (variable name, the node pointed by the 0-edge of  $v$ , the node pointed by the 1-edge of  $v$ )

# Management system: Ensure uniqueness



Node table

node ID	var.	0-edge	1-edge
$N_0$	-	-	-
$N_1$	-	-	-
$N_2$	$x_3$	$N_0$	$N_1$
$N_3$	$x_3$	$N_1$	$N_0$
$N_4$	$x_2$	$N_0$	$N_2$
$N_5$	$x_2$	$N_2$	$N_1$
$N_6$	$x_2$	$N_2$	$N_3$
$N_7$	$x_2$	$N_3$	$N_2$
$N_8$	$x_1$	$N_4$	$N_5$
$N_9$	$x_1$	$N_6$	$N_7$

- In a BDD management system, **node  $v$**  is **represented** as a **triple** of (variable name, the node pointed by the 0-edge of  $v$ , the node pointed by the 1-edge of  $v$ )

# Management system: Ensure uniqueness

- Given a triple as a request for creating a node
  - Check: If the triple is already registered in the node table, return its node ID
  - Otherwise, create a new node
- Node table is implemented by a hash table (triples are used as hash keys)
  - Above check is done in  $O(1)$  time

**Hash table** is the key for managing BDDs efficiently

Node table

node ID	var.	0-edge	1-edge
$N_0$	-	-	-
$N_1$	-	-	-
$N_2$	$x_3$	$N_0$	$N_1$
$N_3$	$x_3$	$N_1$	$N_0$
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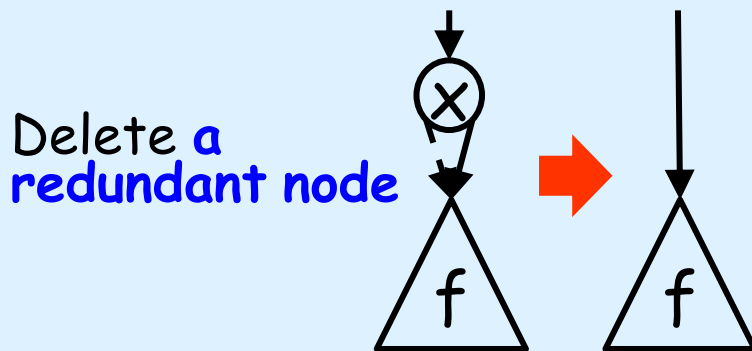
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In case the 0-edge and the 1-edge point to the same node (i.e., same Boolean function), return its node ID



Due to the uniqueness of Boolean functions, the isomorphism of the subgraphs can be checked simply by comparing their node IDs

represented  
nted by the  
edge of  $v$ )

# Node request:

$\text{GetNode}(x, N_{f0}, N_{f1})$

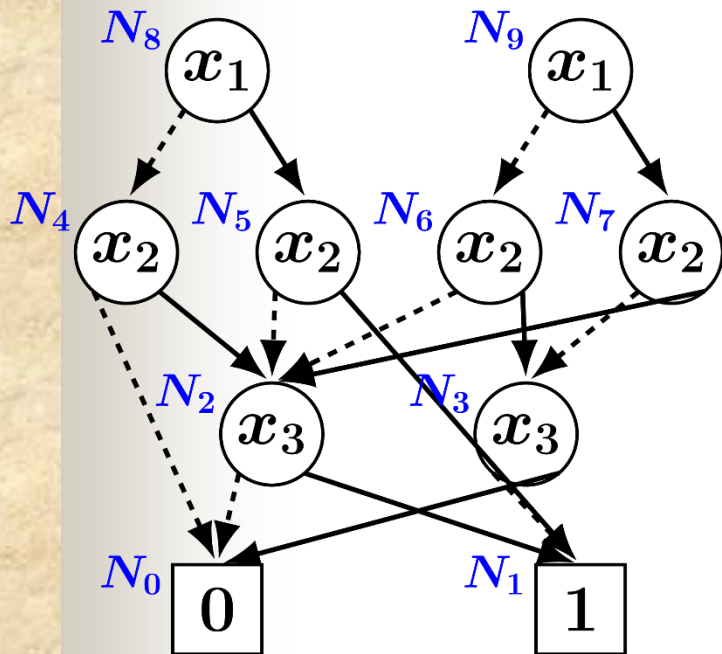
1. If  $N_{f0} = N_{f1}$ , return  $N_{f0}$
2. If triple  $(x, N_{f0}, N_{f1})$  is already registered in the node table, return its node ID
3. Otherwise, register  $(x, N_{f0}, N_{f1})$  in the node table, and return its node ID

# Short break

- Take a deep breath, and relax yourself

# practice: Apply logical operations

- Logical AND of the following two BDDs

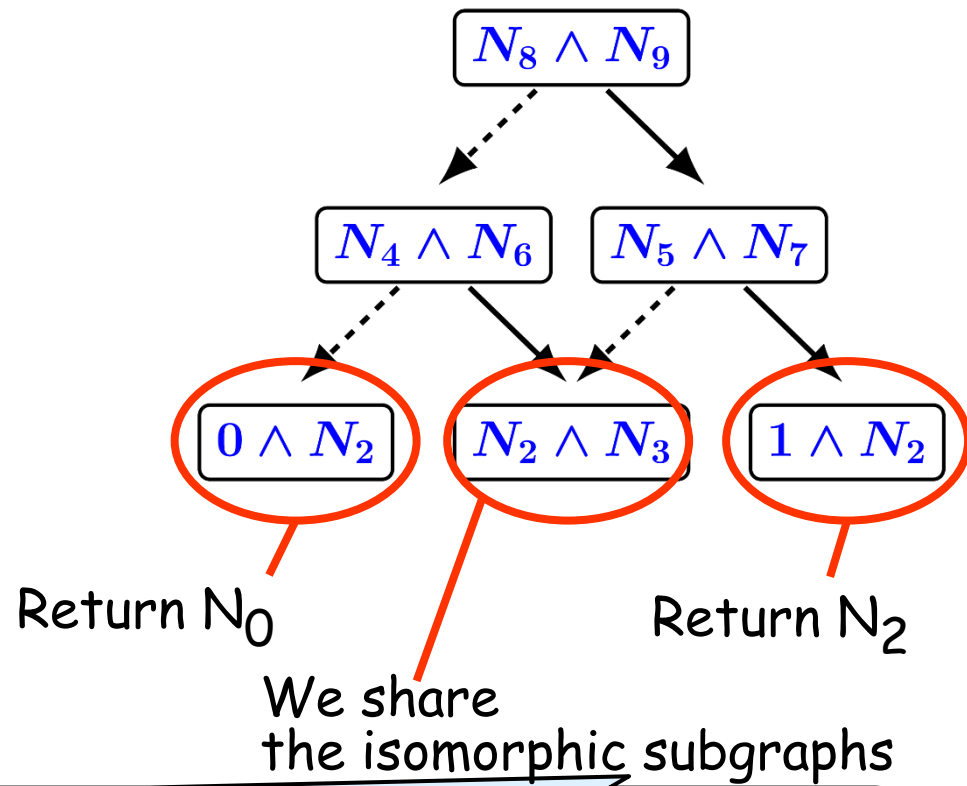
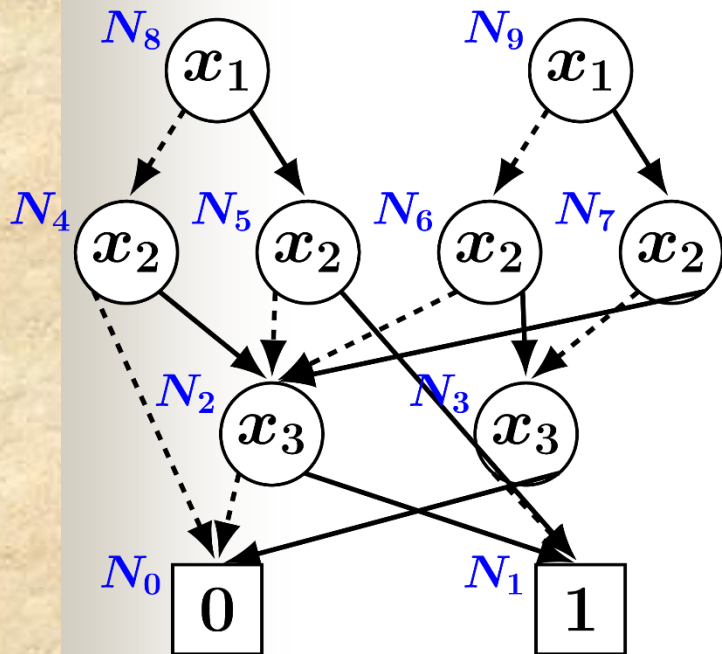


- At first, we create node  $N_i$  pointed by the 0-edge and node  $N_j$  pointed by the 1-edge
- Then,  $\text{GetNode}(x_1, N_i, N_j)$

Recursion to the children pointed by the 0-edges and 1-edges

# practice: Apply logical operations

- Logical AND of the following two BDDs



**GetNode( )** for  $N_2 \wedge N_3$  is called **after creating the subgraphs**

pointed by the 0-edge and the 1-edge of  $N_2 \wedge N_3$

→ The **isomorphic subgraphs** are **created twice**, then they are **shared** ...

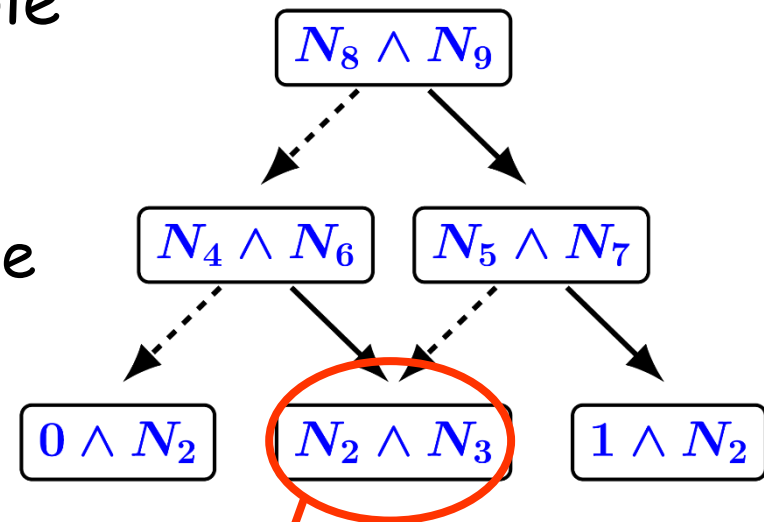
(This approach is time consuming....)

# Management system:

Do not apply the same operation twice (or more)

- Register the results of logical operations in the operation result table (hash table)

- Hash key:  
triple  $(op, N_f, N_g)$ , where  
op is operation ID  
(representing AND, OR, ...),  
 $N_f$  is node ID of node f,  
 $N_g$  is node ID of node g



We share  
the isomorphic subgraphs

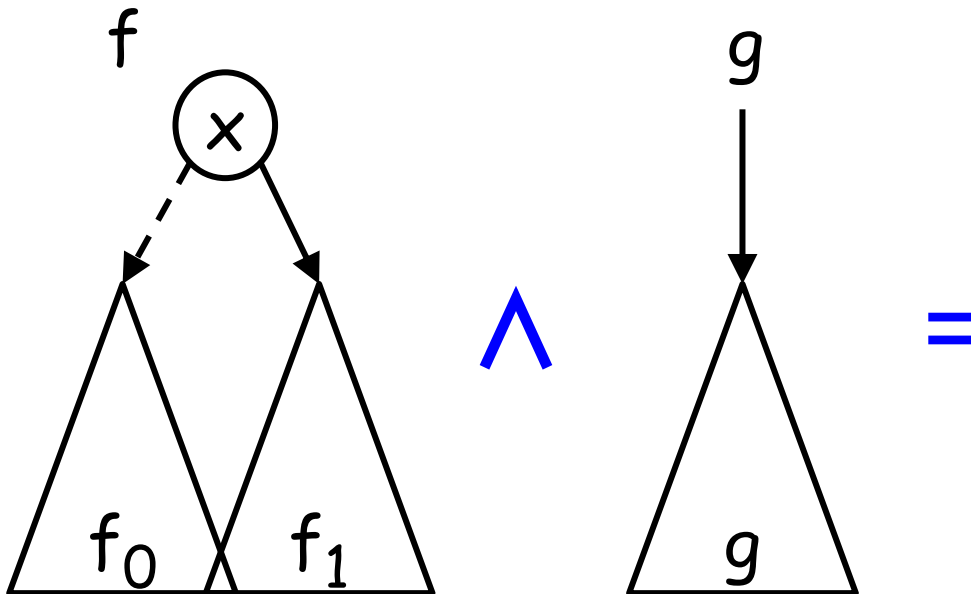
- Operation result table  
returns the node ID of  
the root node of the resulting BDD

p. 4 is the case when the root nodes of  $f$  and  $g$  have the same variable

In case the root nodes of  $f$  and  $g$  have different vars.

By definition,  $f \wedge g = \overline{x}(f_0 \wedge g_0) \vee x(f_1 \wedge g_1)$

In case  $g$  does not depend on  $x$ ?

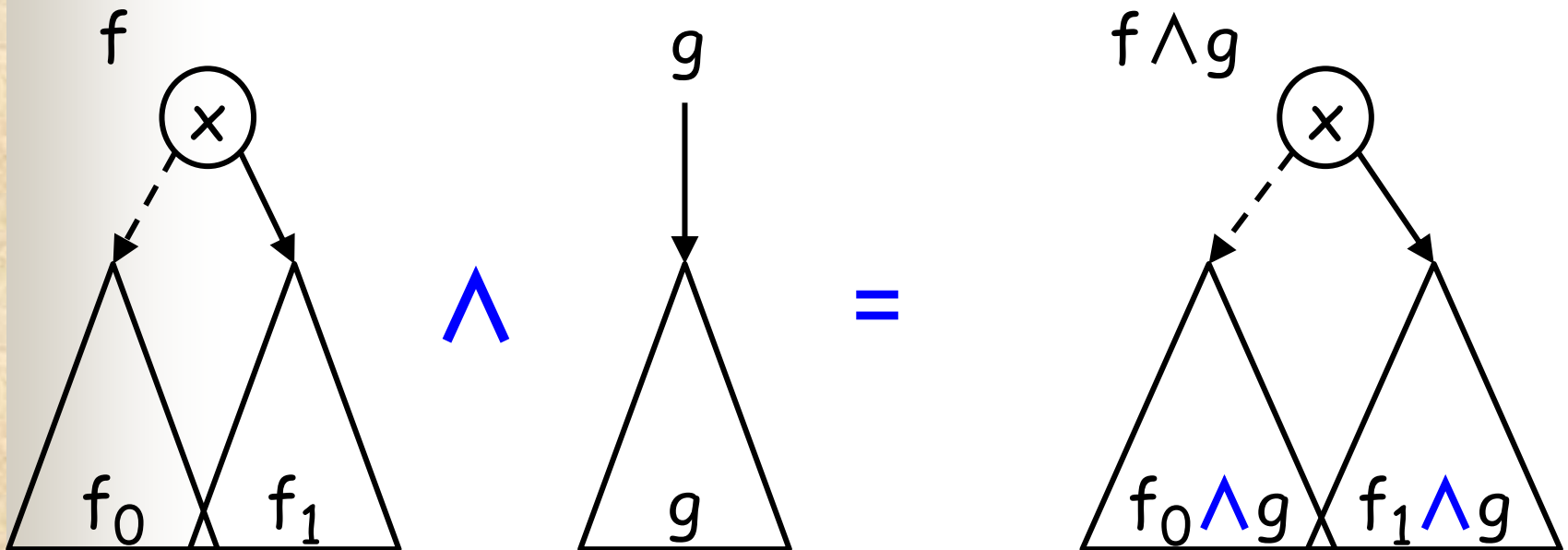


In case the root nodes of  $f$  and  $g$  have different vars.

By definition,  $f \wedge g = \overline{x}(f_0 \wedge g_0) \vee x(f_1 \wedge g_1)$

In case  $g$  does not depend on  $x$ ?

$$f \wedge g = \overline{x}(f_0 \wedge g) \vee x(f_1 \wedge g)$$



# Apply operation

## $\text{Apply}(\text{op}, N_f, N_g)$

$N_f: (x_f, N_{f0}, N_{f1})$

$N_g: (x_g, N_{g0}, N_{g1})$

1. If at least one of  $N_f$  and  $N_g$  is a constant node, or if  $N_f = N_g$  holds, return the node ID of the resulting BDD (according to op)  
(e.g.,  $0 \wedge N_f = 0$ ,  $1 \wedge N_f = N_f$ ,  $N_f \wedge N_f = N_f$ )
2. If  $(\text{op}, N_f, N_g)$  is registered in the operation result table, return the node ID of the result
3. If variables  $x_f$  and  $x_g$  are the same
  - 3-1.  $N_{h0} := \text{Apply}(\text{op}, N_{f0}, N_{g0})$ ,  $N_{h1} := \text{Apply}(\text{op}, N_{f1}, N_{g1})$
  - 3-2. If  $N_{h0} = N_{h1}$  holds, return  $N_{h0}$Otherwise, return the resulting node ID of  $\text{GetNode}(x_f, N_{h0}, N_{h1})$
4. If variable  $x_f$  appears in higher level than  $x_g$ 
  - 4-1.  $N_{h0} := \text{Apply}(\text{op}, N_{f0}, N_g)$ ,  $N_{h1} := \text{Apply}(\text{op}, N_{f1}, N_g)$
  - 4-2. Same as 3-2
5. If variable  $x_f$  appears in lower level than  $x_g$ 
  - Same as 4 (exchange the roles of  $N_f$  and  $N_g$ )

# Time complexity of Apply operation

- Worst-case time complexity:  $O(|f| |g|)$ 
  - This is because the size of the resulting BDD of the operation can be  $O(|f| |g|)$
- For a long time, the time complexity is believed to be less than  $O(|f| |g|)$  in case the size of the resulting BDD is small
- Unfortunately, however, it is proved that “even if the sizes of the input and result BDDs are small, there exists an instance that requires  $O(|f| |g|)$  time” [ Yoshinaka et al. 2012 ]
- Empirically, in many cases, we can apply operations within the time proportional to  $|f| + |g|$

By utilizing hash tables

## Extra: Reference counter

- Reference count of node  $v$ :
  - The number of reference from other nodes (i.e., in-degree of  $v$ ; how many times node  $v$  is pointed from other nodes)
- In many BDD management systems, reference counter is used in the node table
- How to use reference counter?
  - Repetition of `GetNode( )` (i.e., creating nodes) floods the node table
  - Garbage collection: Recycle nodes of reference count 0
- Things to consider
  - Recycled nodes still exist in the operation result table
    - We need to clear the operation result table (whole table)
  - Suppose that we recycle a node in each time when the reference count becomes 0 (which means clearing the op. table)
    - The efficiency of the operation result table is spoiled
  - Garbage collection is done when the node table is almost full

## practice: Create BDDs

- Represent the following Boolean functions by BDDs

1. AND:  $x_1 x_2 x_3 x_4$

2. OR:  $x_1 \vee x_2 \vee x_3 \vee x_4$

3. Combination of AND and OR:  $(x_1 \vee x_2) x_3$

4. Exclusive-OR (XOR):  $x_1 \oplus x_2 \oplus x_3 \oplus x_4$

- Three ways for creating BDDs

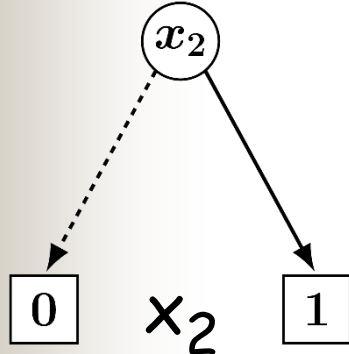
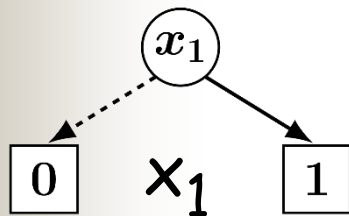
- Create a truth table  $\rightarrow$  decision tree  $\rightarrow$  BDD

- Create a BDD from top by considering the subfunctions  
(p. 6)

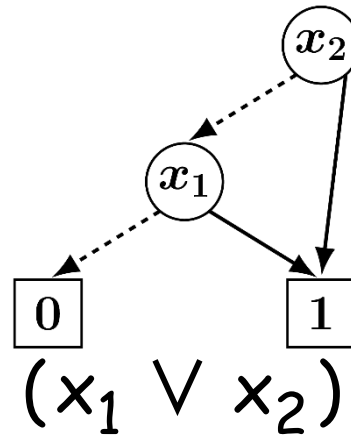
- Create a BDD by Apply operations (see the following page)

# Create a BDD by Apply operations

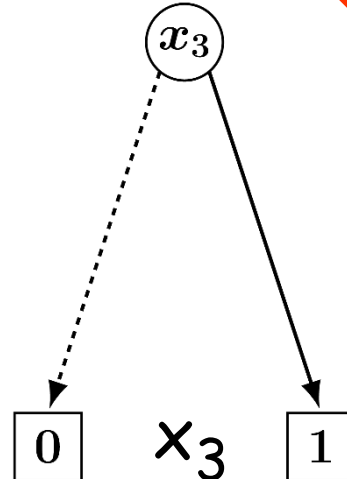
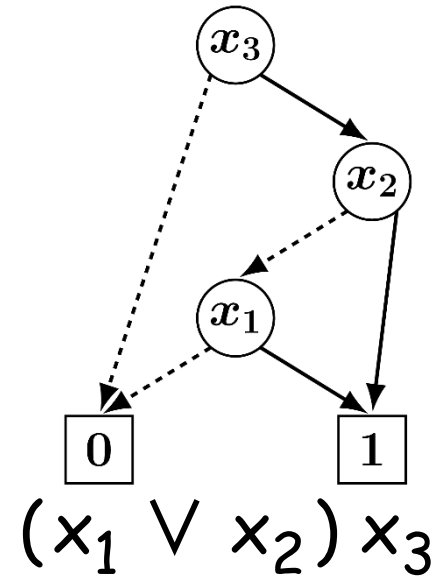
■  $(x_1 \vee x_2) x_3$



$\vee$



$\wedge$



In BDD management systems,  
BDDs are processed as a form of  
shared BDDs

# Summary

- Binary Decision Diagram (BDD)
- Apply operations on two BDDs
  - Recursion

## Techniques for efficient manipulation

- Shared BDDs: Uniqueness of Boolean functions
- Two hash tables for efficient operations
  - Node table:
    - Ensure the uniqueness  
i.e., do not create equivalent nodes twice (or more)
  - Operation result table:
    - Do not apply the same operation twice (or more)