

Large-Scale Knowledge Processing

# Using Binary Decision Diagrams (1)



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# Prev. class: Binary Decision Diagram (BDD)

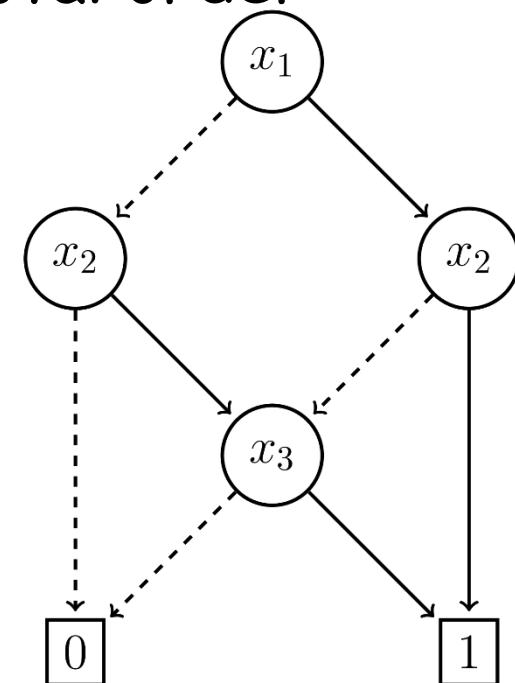
- Representation of Boolean functions by a **directed acyclic graph**

- **Variable order**

- Variables appear according to a total order

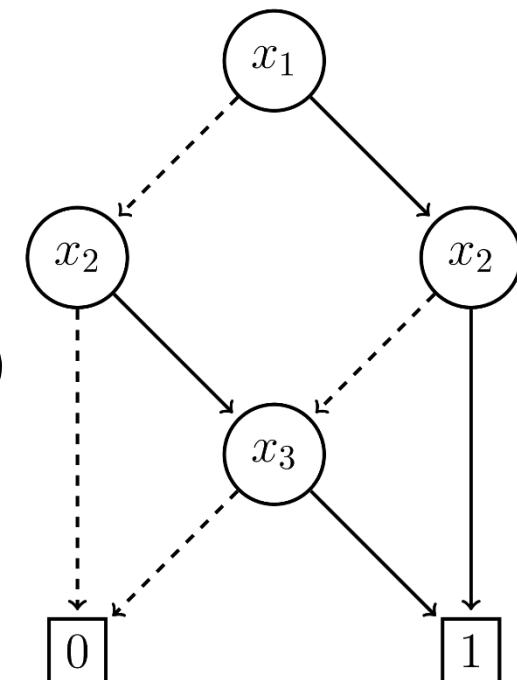
- Two rules for simplifying BDDs

- Remove **redundant nodes**
  - Share **equivalent nodes**
  - **Reduce** BDDs until we have no redundant and equivalent nodes



# Prev. class: Binary Decision Diagram (BDD)

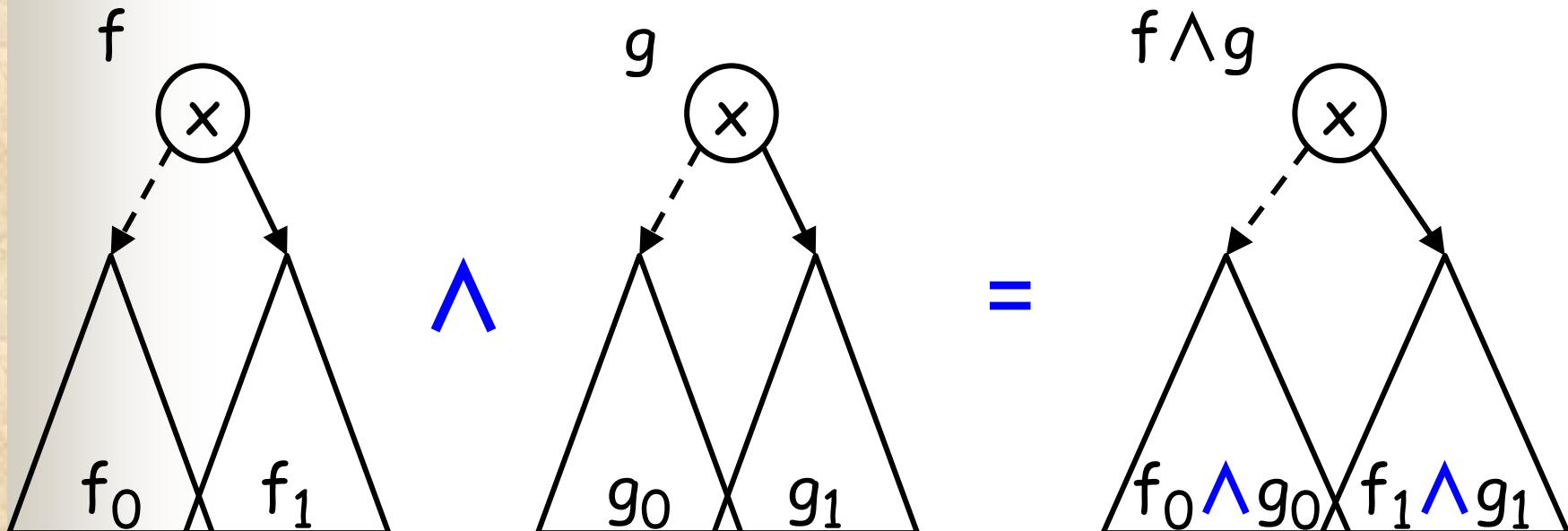
- Representation of Boolean functions by a **directed acyclic graph**
- The **representation is unique** if variable order is defined
- Many practical Boolean functions are **compactly** represented  
(We can efficiently compress logical structures)
- **Efficient operations** for BDDs  
[Bryant 1986]
- Applications in various fields



# Logical operations (Boolean operations)

- Logical AND of  $f = \overline{x} f_0 \vee x f_1$   
and  $g = \overline{x} g_0 \vee x g_1$
- $f \wedge g = \overline{x} (\underline{f_0 \wedge g_0}) \vee x (\underline{f_1 \wedge g_1})$

We can obtain these ANDs recursively

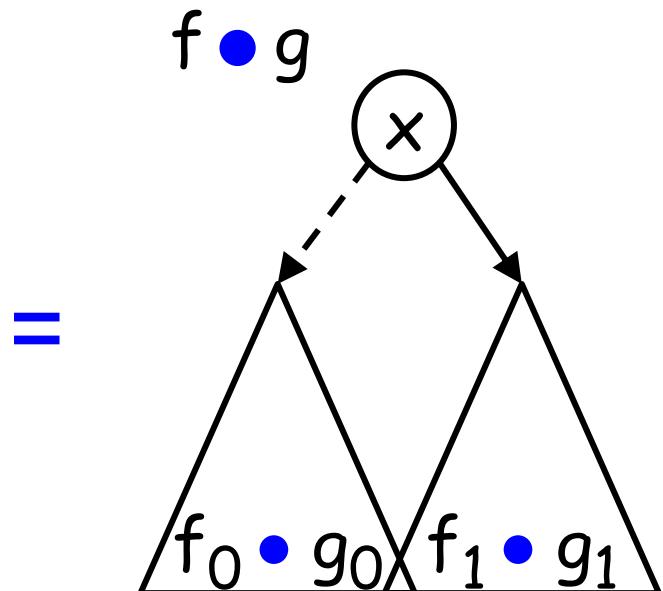
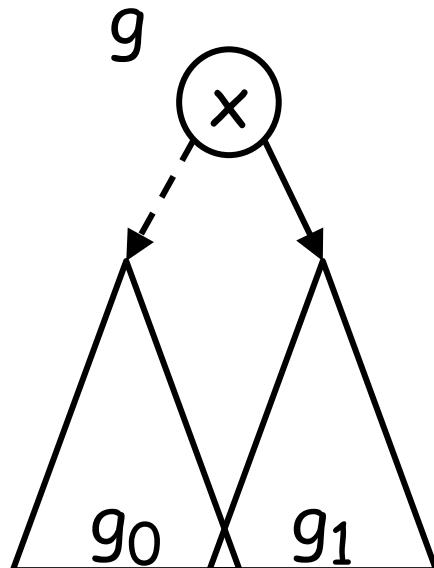
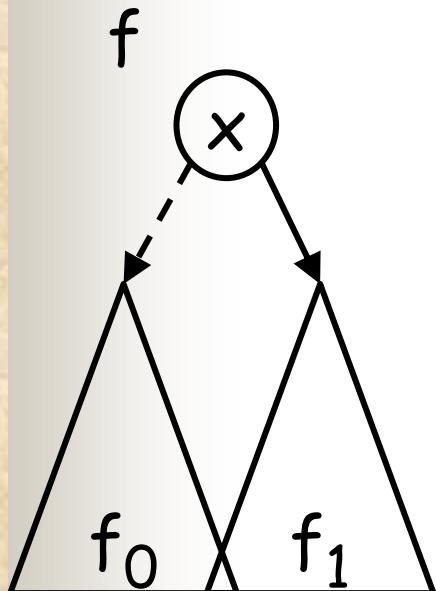


# Logical operations (Boolean operations)

AND, OR, XOR, ...

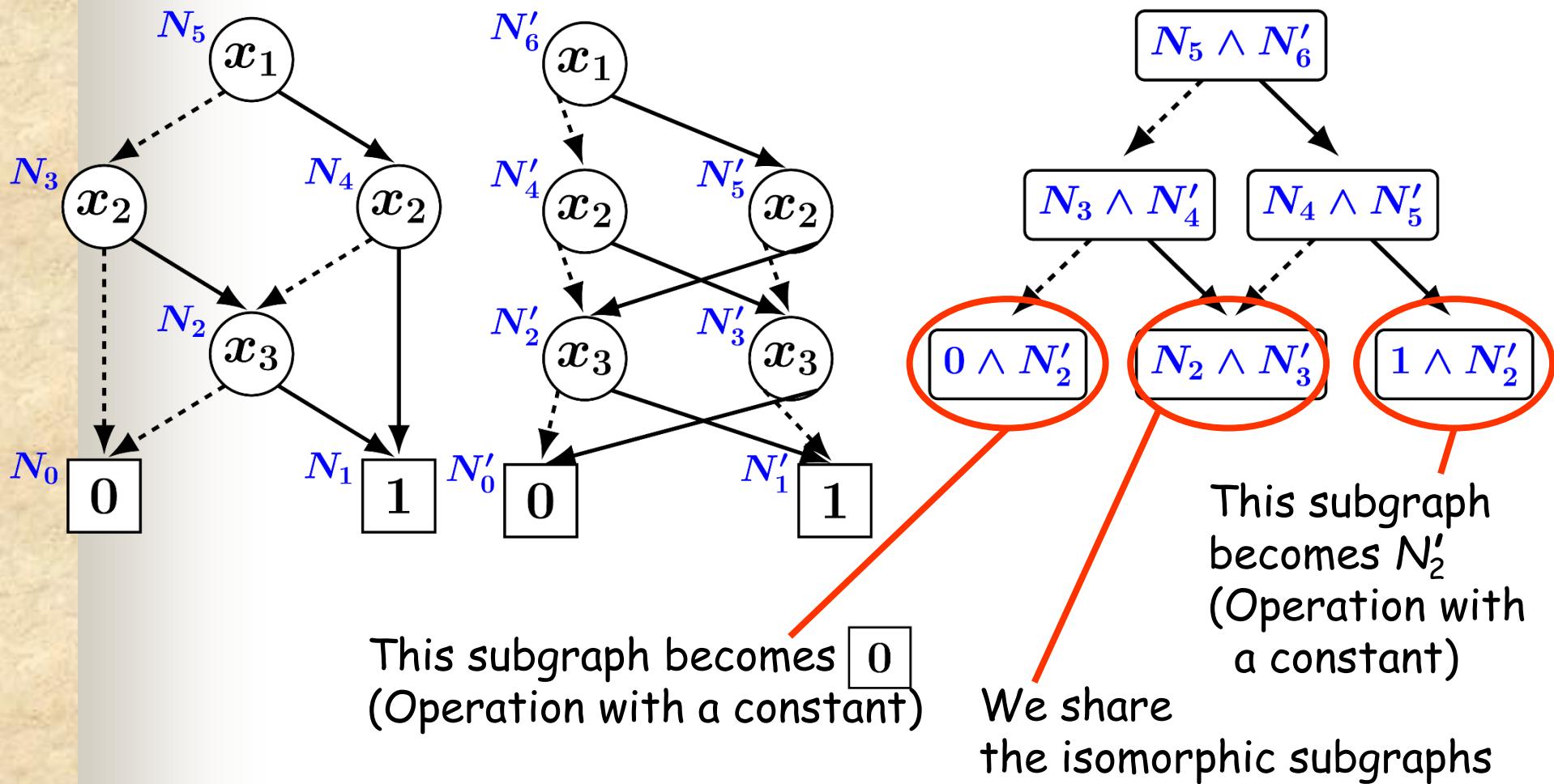
- Binary operation of  $f = \overline{x} f_0 \vee x f_1$   
and  $g = \overline{x} g_0 \vee x g_1$
- $f \bullet g = \overline{x} (\underline{f_0 \bullet g_0}) \vee x (\underline{f_1 \bullet g_1})$

We can obtain these recursively



# practice: Apply logical operations

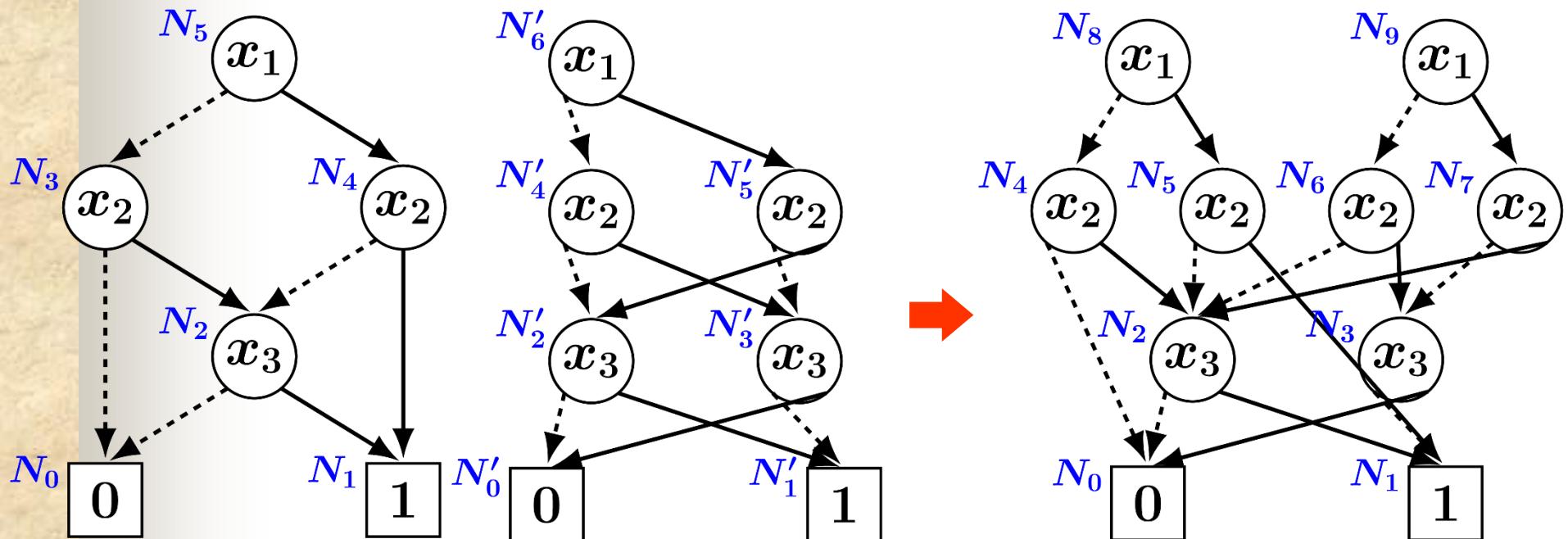
- Logical AND of the following two BDDs



# Short break

- Take a deep breath, and relax yourself

# Shared BDDs

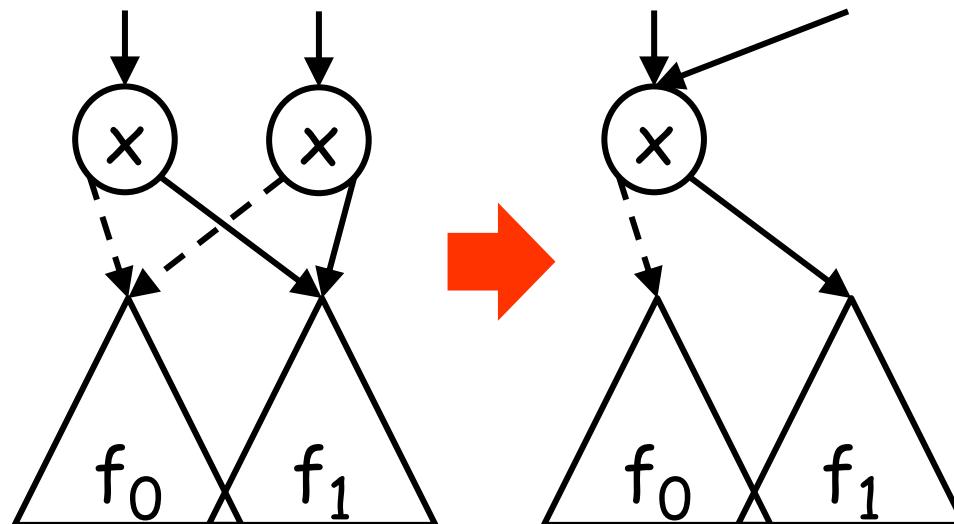


- By using the same variable order for representing BDDs, we can **share equivalent nodes** of two (or more) BDDs  
→ **Uniqueness** of Boolean functions in a BDD management system  
(No two BDDs represent the same Boolean function)

# Management system: Ensure uniqueness

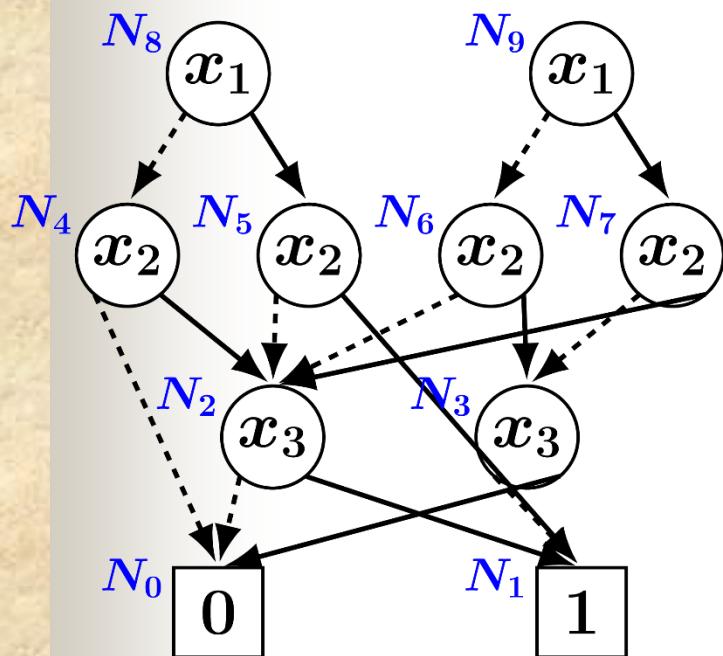
- **Equivalent nodes should be shared**  
(No equivalent nodes in a BDD management system)

Share **equivalent nodes**



- In a BDD management system, **node  $v$  is represented as a triple** of (variable name, the node pointed by the 0-edge of  $v$ , the node pointed by the 1-edge of  $v$ )

# Management system: Ensure uniqueness



Node table

node ID	var.	0-edge	1-edge
$N_0$	-	-	-
$N_1$	-	-	-
$N_2$	$x_3$	$N_0$	$N_1$
$N_3$	$x_3$	$N_1$	$N_0$
$N_4$	$x_2$	$N_0$	$N_2$
$N_5$	$x_2$	$N_2$	$N_1$
$N_6$	$x_2$	$N_2$	$N_3$
$N_7$	$x_2$	$N_3$	$N_2$
$N_8$	$x_1$	$N_4$	$N_5$
$N_9$	$x_1$	$N_6$	$N_7$

- In a BDD management system, node  $v$  is represented as a **tuple** of (variable name, the node pointed by the 0-edge of  $v$ , the node pointed by the 1-edge of  $v$ )

# Management system: Ensure uniqueness

- Given a triple as a request for creating a node
  - Check: If the triple is already registered in the node table, return its node ID
  - Otherwise, create a new node
- Node table is implemented by a hash table (triples are used as hash keys)
  - Above check is done in  $O(1)$  time
- In a BDD management system, **node v** is represented as a **triple** of (variable name, the node pointed by the 0-edge of v, the node pointed by the 1-edge of v)

Node table

node ID	var.	0-edge	1-edge
$N_0$	-	-	-
$N_1$	-	-	-
$N_2$	$x_3$	$N_0$	$N_1$
$N_3$	$x_3$	$N_1$	$N_0$
$N_4$	$x_2$	$N_0$	$N_2$
$N_5$	$x_2$	$N_2$	$N_1$
$N_6$	$x_2$	$N_2$	$N_3$
$N_7$	$x_2$	$N_3$	$N_2$
$N_8$	$x_1$	$N_4$	$N_5$
$N_9$	$x_1$	$N_6$	$N_7$

Hash table is the key for managing BDDs efficiently

# Management system: Ensure uniqueness

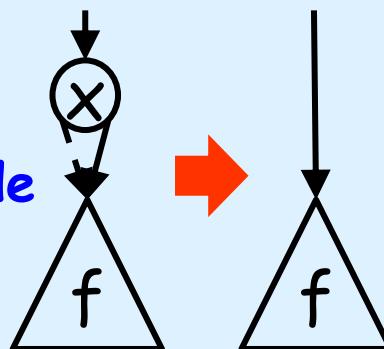
- Given a triple as a request for creating a node
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Node table

node ID	var.	0-edge	1-edge
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$N_2$	$x_3$	$N_0$	$N_1$
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$N_9$		$N_6$	$N_7$

In case the 0-edge and the 1-edge point to the same node (i.e., same Boolean function), return its node ID

Delete a redundant node



Due to the uniqueness of Boolean functions, the isomorphism of the subgraphs can be checked simply by comparing their node IDs

represented by the edge of v)

# Node request: GetNode( $x, N_{f0}, N_{f1}$ )

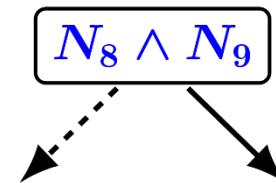
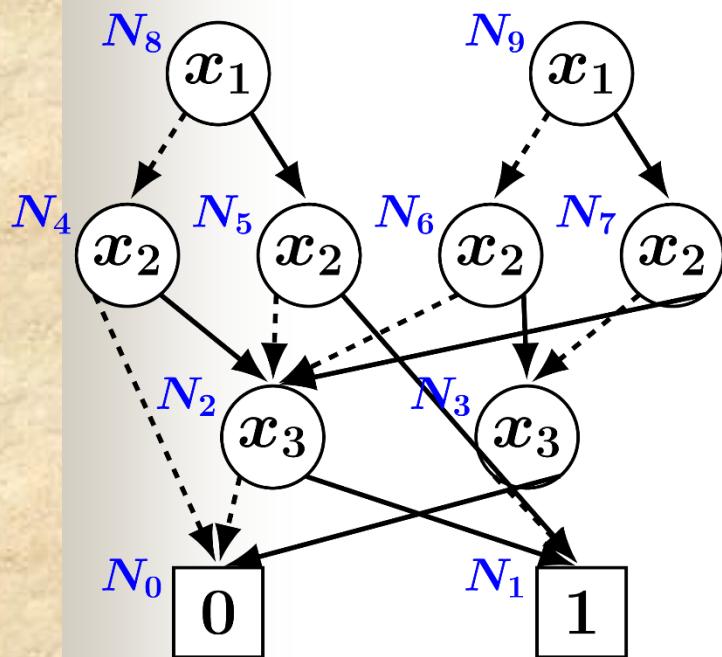
1. If  $N_{f0} = N_{f1}$ , return  $N_{f0}$
2. If triple  $(x, N_{f0}, N_{f1})$  is already registered in the node table, return its node ID
3. Otherwise, register  $(x, N_{f0}, N_{f1})$  in the node table, and return its node ID

# Short break

- Take a deep breath, and relax yourself

# practice: Apply logical operations

- Logical AND of the following two BDDs

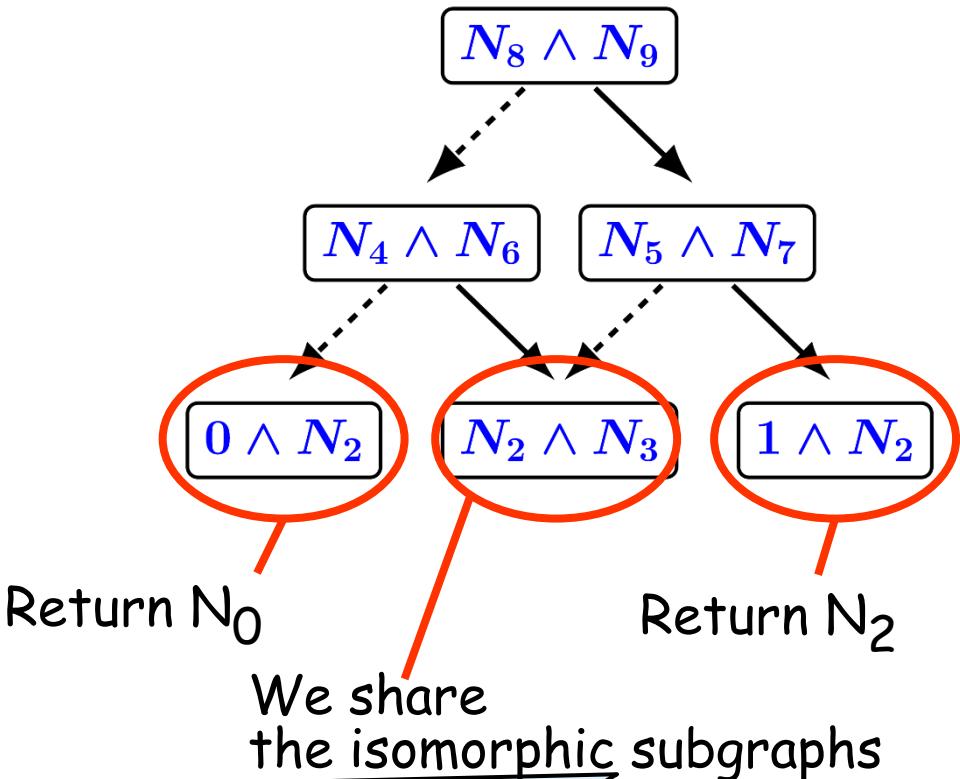
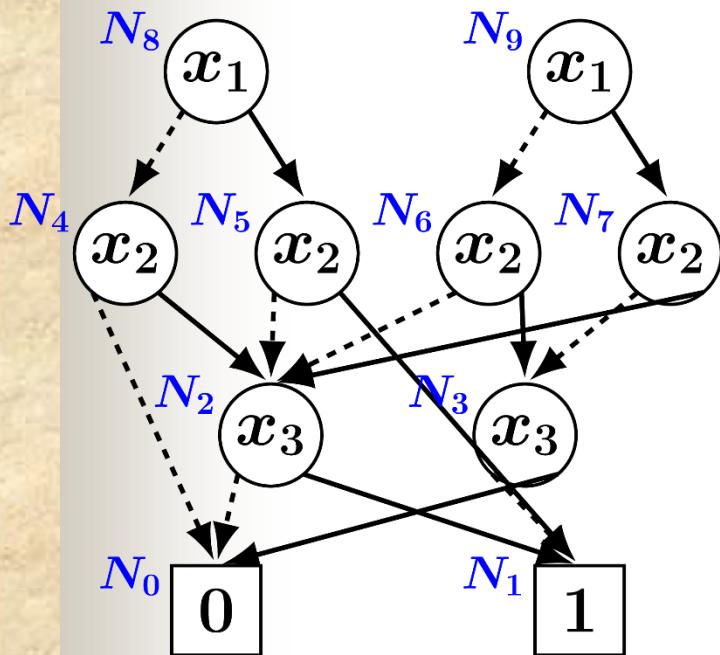


- At first, we create node  $N_i$  pointed by the 0-edge and node  $N_j$  pointed by the 1-edge
- Then,  $\text{GetNode}(x_1, N_i, N_j)$

Recursion to the children pointed by the 0-edges and 1-edges

# practice: Apply logical operations

- Logical AND of the following two BDDs



`GetNode( )` for  $N_2 \wedge N_3$  is called **after creating the subgraphs**

pointed by the 0-edge and the 1-edge of  $N_2 \wedge N_3$

→ The **isomorphic subgraphs** are **created twice, then they are shared** ...

(This approach is time consuming....)

# Management system: Do not apply the same operation twice (or more)

- Register the results of logical operations in the operation result table (hash table)

- Hash key:

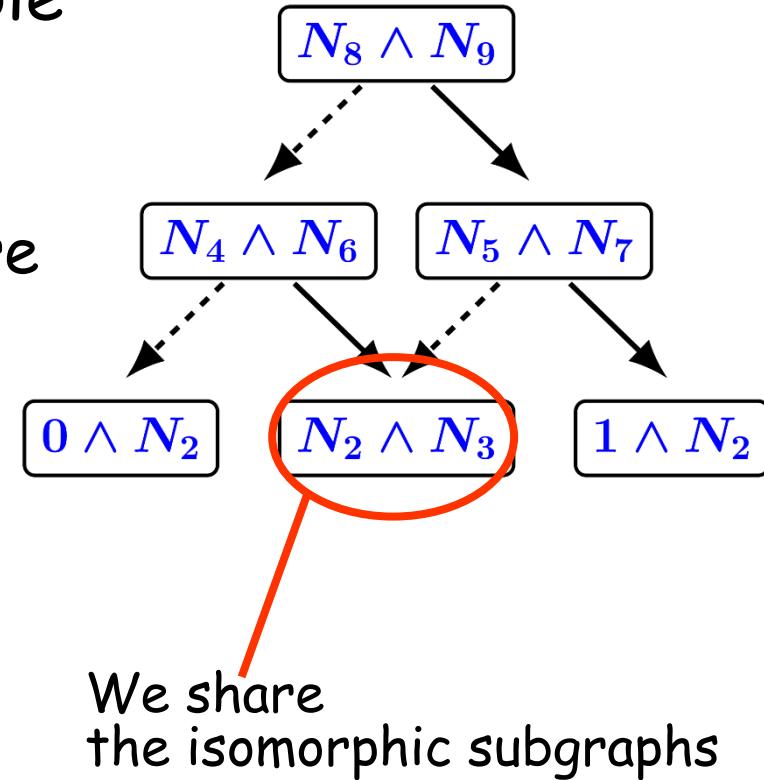
- triple  $(op, N_f, N_g)$ , where  $op$  is operation ID

- (representing AND, OR, ...),

- $N_f$  is node ID of node  $f$ ,

- $N_g$  is node ID of node  $g$

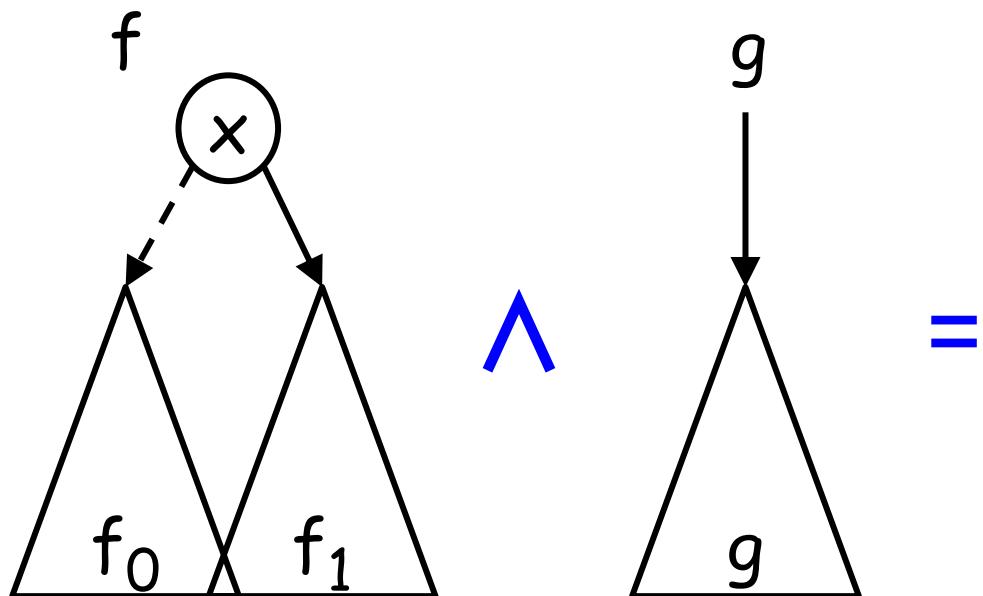
- Operation result table returns the node ID of the root node of the resulting BDD



In case the root nodes of  $f$  and  $g$  have different vars.

By definition,  $f \wedge g = \overline{x}(f_0 \wedge g_0) \vee x(f_1 \wedge g_1)$

In case  $g$  does not depend on  $x$  ?

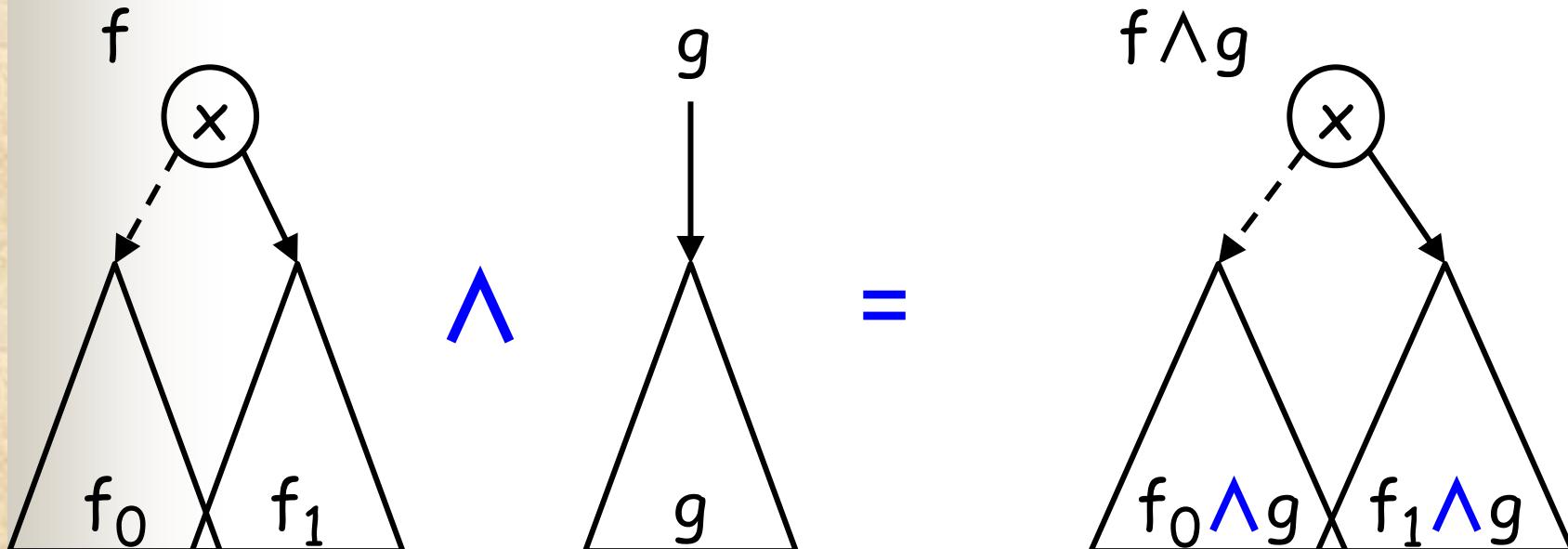


In case the root nodes of  $f$  and  $g$  have different vars.

By definition,  $f \wedge g = \overline{x}(f_0 \wedge g_0) \vee x(f_1 \wedge g_1)$

In case  $g$  does not depend on  $x$  ?

$$f \wedge g = \overline{x}(f_0 \wedge g) \vee x(f_1 \wedge g)$$



# Apply operation

Apply(op,  $N_f$ ,  $N_g$ )

$N_f$ : ( $x_f$ ,  $N_{f0}$ ,  $N_{f1}$ )

$N_g$ : ( $x_g$ ,  $N_{g0}$ ,  $N_{g1}$ )

1. If at least one of  $N_f$  and  $N_g$  is a constant node, or if  $N_f = N_g$  holds, return the node ID of the resulting BDD (according to op)  
(e.g.,  $0 \wedge N_f = 0$ ,  $1 \wedge N_f = N_f$ ,  $N_f \wedge N_f = N_f$ )
2. If  $(op, N_f, N_g)$  is registered in the operation result table, return the node ID of the result
3. If variables  $x_f$  and  $x_g$  are the same
  - 3-1.  $N_{h0} := \text{Apply}(op, N_{f0}, N_{g0})$ ,  $N_{h1} := \text{Apply}(op, N_{f1}, N_{g1})$
  - 3-2. If  $N_{h0} = N_{h1}$  holds, return  $N_{h0}$   
Otherwise, return the resulting node ID of  $\text{GetNode}(x_f, N_{h0}, N_{h1})$
4. If variable  $x_f$  appears in higher level than  $x_g$ 
  - 4-1.  $N_{h0} := \text{Apply}(op, N_{f0}, N_g)$ ,  $N_{h1} := \text{Apply}(op, N_{f1}, N_g)$
  - 4-2. Same as 3-2
5. If variable  $x_f$  appears in lower level than  $x_g$ 
  - Same as 4 (exchange the roles of  $N_f$  and  $N_g$ )

# Time complexity of Apply operation

- Worst-case time complexity:  $O(|f| |g|)$ 
  - This is because the size of the resulting BDD of the operation can be  $O(|f| |g|)$
- For a long time, the time complexity is believed to be less than  $O(|f| |g|)$  in case the size of the resulting BDD is small
- Unfortunately, however, it is proved that "even if the sizes of the input and result BDDs are small, there exists an instance that requires  $O(|f| |g|)$  time"  
[ Yoshinaka et al. 2012 ]
- Empirically, in many cases, we can apply operations within the time proportional to  $|f| + |g|$

By utilizing hash tables

# Extra: Reference counter

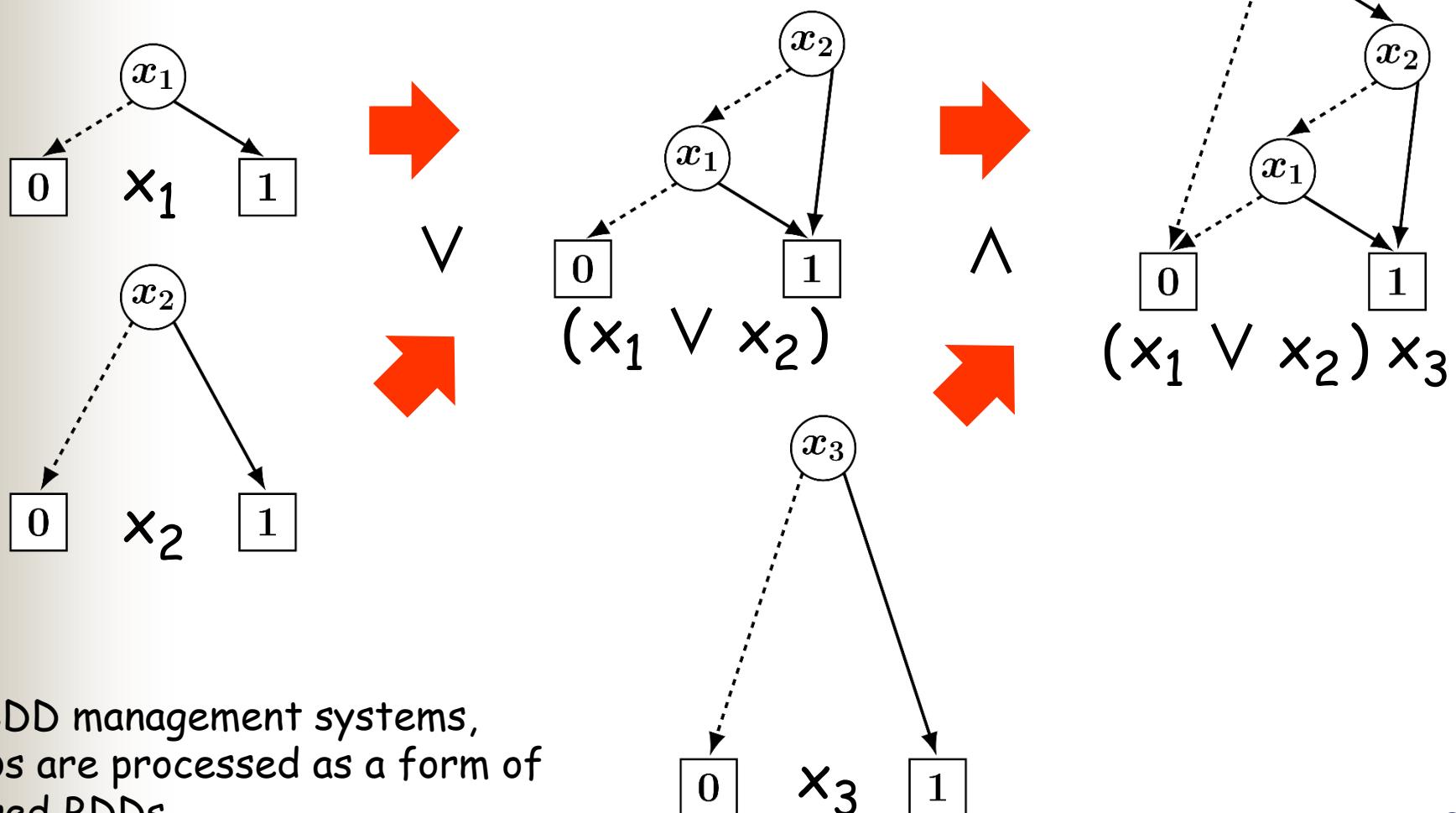
- Reference count of node  $v$ :
  - The number of reference from other nodes (i.e., in-degree of  $v$ ; how many times node  $v$  is pointed from other nodes)
- In many BDD management systems, reference counter is used in the node table
- How to use reference counter?
  - Repetition of `GetNode()` (i.e., creating nodes) floods the node table
  - Garbage collection: Recycle nodes of reference count 0
- Things to consider
  - Recycled nodes still exist in the operation result table
    - We need to clear the operation result table (whole table)
  - Suppose that we recycle a node in each time when the reference count becomes 0 (which means clearing the op. table)
    - The efficiency of the operation result table is spoiled
  - Garbage collection is done when the node table is almost full

## practice: Create BDDs

- Represent the following Boolean functions by BDDs
  1. AND:  $x_1 \times_2 \times_3 \times_4$
  2. OR:  $x_1 \vee x_2 \vee x_3 \vee x_4$
  3. Combination of AND and OR:  $(x_1 \vee x_2) \times_3$
  4. Exclusive-OR (XOR):  $x_1 \oplus x_2 \oplus x_3 \oplus x_4$
- Three ways for creating BDDs
  - Create a truth table → decision tree → BDD
  - Create a BDD from top by considering the subfunctions  
(p. 6)
  - Create a BDD by Apply operations (see the following page)

# Create a BDD by Apply operations

- $(x_1 \vee x_2) x_3$



In BDD management systems,  
BDDs are processed as a form of  
shared BDDs

# Summary

- Binary Decision Diagram (BDD)
- Apply operations on two BDDs
  - Recursion

Techniques for efficient manipulation

- Shared BDDs: Uniqueness of Boolean functions
- Two hash tables for efficient operations
  - Node table:
    - Ensure the uniqueness  
i.e., do not create equivalent nodes twice (or more)
  - Operation result table:
    - Do not apply the same operation twice (or more)